| design | $\emptyset 58 \times 78 \mathrm{~mm}$ |  |
| :---: | :---: | :---: |
| incremental | number of pulses | 10 to 5000 |
| $\checkmark$ encoder with shaft $\varnothing 6 \mathrm{~mm}$ |  |  |
| $\checkmark$ resolution up to $\mathbf{5 0 0 0}$ pulses/rotations |  |  |
| $\checkmark$ high rotational speed up to 10000 min- ${ }^{1}$ |  |  |
| $\checkmark$ optical sensing principle |  |  |
| $\checkmark$ compensation of ageing and temperature drift |  |  |
| $\checkmark$ compensation in case of a soiled encoder disc |  |  |
| high sig tary out | ise ratio thanks ls | plemen- |

## angular, linear and

speed measurement

## description

Incremental encoders are used to detect angle of rotation and rotary speeds. To measure length or position, connect the encoder to a driveshaft using a flexible coupling or directly by way of a friction wheel or pinion.
When measuring length using incremental encoders, the square wave signals, emitted by the encoder on its signal lines, are counted. The resolution can be influenced by selecting the number of encoder pulses per rotation.
Incremental encoders operate using photoelectric scanning. Infrared light that is emitted by a temperature controlled LED passes through a mask and a code disc and produces a light proportional DC signal on the optical diodes. When the shaft turns, periodic signals, similar to sine waves, result on the optical diodes. The number of signal periods per rotation corresponds to the number of markings on the encoder disc.
To increase immunity to interference each channel is scanned differentially.
A light-intensity controller compensates both for the temperature and/or ageing drift and for any soiling of the glass encoder disc.
Incremental encoders lose their current measured value when the control is turned off or after a power failure. In order to allow an angle position for any given position to be referenced
again, a zero pulse is used that is transmitted once per rotation thus providing an absolute marker.
Incremental encoders emit two output signals in 900 phase quadrature thus allowing the direction of rotation to be determined.
Linking the two square wave signals together with a pulse edge evaluation allows the number of pulses per rotation to be quadrupled. To ensure a clear marker is obtained from the zero pulse even with pulse quadrupling, its pulse width is one quarter of the period width of one signal.
As the signals from the incremental encoders are counted during the evaluation, noise pulses on the signal lines are bound to cause false counts. For this reason special emphasis must be placed on a particularly large signal-to-noise ratio. In practice the signal-to-noise ratio is doubled by outputting the complementary (i.e. the inverted) pulses on two different tracks in addition to the pulse signals in phase quadrature.

## application examples

angular measurement at bending machines

- linear measurement at conveyor systems
speed measurement at wind-up units


## WEGMESSSYSTEME

IPF ELECTRONIC
DREHGEBER 1200

| article no. | VD580536 | VD580538 | VD580539 | VD580540 | VD580541 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| pulses (per rotation) | 10 | 30 | 50 | 60 | 100 |
| article no. | VD580506 | VD580513 | VD580514 | VD580515 | VD580522 |
| pulses (per rotation) | 200 | 360 | 400 | 500 | 1000 |
| article no. | VD580523 | VD580526 | VD580528 | VD580529 | VD580530 |
| pulses (per rotation) | 1024 | 1500 | 2000 | 2048 | 2500 |
| article no. | VD580531 | VD580535 |  |  |  |
| pulses (per rotation) | 3600 | 5000 |  |  |  |

TECHNCAL DATA

| rotation speed | max. 10.000 min $^{-1}$ |
| :---: | :---: |
| pulses (per rotation) | s. above |
| output signal | push-pull: A, A inverse, B, B inverse, $N, N$ inverse reference signal: zero pulse width $90^{\circ}$ |
| output frequency | max. 150kHz |
| voltage supply | 4.75 ... 30V DC |
| current consumption (w/o load) | 40 mA |
| output current (max. load) | 40mA (6-channel) |
| starting torque | IP54: $\leq 0.015 \mathrm{Ncm} /$ IP65: $\leq 0.03 \mathrm{Ncm}$ (option) |
| load capacity of shaft | axial 10N / radial 20 N |
| moment of inertia (rotor) | $14.5 \mathrm{gcm}^{2}$ |
| vibration resistance | 10g, $16 \ldots 2000 \mathrm{~Hz}$ |
| shock resistance | 200g, 2 ms |
| short-circuit protection | + |
| material (housing) | aluminum |
| dimensions | $\emptyset 58 \mathrm{~mm} / \mathrm{shaft}$ : $\varnothing 6 \times 10 \mathrm{~mm}$ |
| temperature (operating) | $-25 \ldots+85^{\circ} \mathrm{C}$ |
| humidity | 95\% non-condensing |
| weight | approx. 0.25 kg |
| degree of protection (EN 60529) | without shaft seal: IP54 / with shaft seal: IP65 (option) |
| connectgion | M23 flange connector, 12-in. axial |
| connection accessories | e.g. AV000023 |

